

M-10iD/12



Max. load capacity at wrist: 12 kg



Max. reach: 1441 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | Moments (N-m)/Inertia (kg-m ²) | | | Protection | | |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|-----|-----|-----|-----|-----|--|-------------------|-------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | J4 Moment/Inertia | J5 Moment/Inertia | J6 Moment/Inertia | Average Power consumption (kW) | Body standard/optional | Wrist & J3 arm standard/optional |
| M-10 | iD | 12 | 12 | 1441 | 6 | ±0.02** | 145 | 340 (370) | 235 | 455 | 380 | 360 | 900 | 260 | 240 | 260 | 430 | 450 | 720 | 26/9 | 26/9 | 11/3 | 1 | IP54/ IP65 | IP67 |

● standard ○ on request - not available ** Based on ISO9283

M-10iD/12 Hollow Wrist



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